Theory of acoustic surface plasmons

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I. INTRODUCTION

Recently, a low-energy collective excitation has been predicted to exist at metal surfaces where a quasi two-dimensional (2D) surface-state band coexists with the underlying three-dimensional (3D) continuum. Here we present a model in which the screening of a semiinfinite 3D metal is incorporated into the description of electronic excitations in a 2D electron gas through the introduction of an effective 2D dielectric function. Our self-consistent calculations of the dynamical response of the 3D substrate indicate that an acoustic surface plasmon exists for all possible locations of the 2D sheet relative to the metal surface. This low-energy excitation, which exhibits linear dispersion at low wave vectors, is dictated by the nonlocality of the 3D dynamical response providing incomplete screening of the 2D electron-density oscillations.

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II. THEORY

A variety of metal surfaces, such as Be(0001) and the (111) surfaces of the noble metals Cu, Ag, and Au, are known to support a partially occupied band of Shockley surface states with energies near the Fermi level. Since the wave function of these states is strongly localized near the surface and decays exponentially into the solid, they can be considered to form a 2D electron gas.

In order to describe the electronic excitations occurring within a surface-state band that is coupled with the underlying continuum of valence electrons in the metal, we consider a model in which surface-state electrons comprise a 2D electron gas at $z = z_d$ ($z$ denotes the coordinate normal to the surface).
surface), while all other states of the metal comprise a 3D substrate consisting of a fixed uniform positive background (jellium) of density

$$n_s(z) = \begin{cases} \bar{n}, & z \approx 0, \\ 0, & \text{elsewhere}, \end{cases}$$

(1)

plus a neutralizing inhomogeneous cloud of interacting electrons. The positive-background charge density \(\bar{n}\) is often expressed in terms of the 3D Wigner radius \(r_{2D} = (3/4\pi \bar{n})^{1/3}/a_0\), where \(a_0 = 0.529 \text{ Å}\) being the Bohr radius.

We consider the response of the interacting 2D and 3D electronic subsystems to an external potential \(\delta \Phi_{ext}(r, \omega)\). According to time-dependent perturbation theory, keeping only terms of first order in the external perturbation, and Fourier transforming in two directions, the electron densities induced in the 2D and 3D subsystems are found to be

$$\delta n_{2D}(z, q, \omega) = \delta (z - z_d) \chi_{2D}(q, \omega) \left[ \delta \Phi_{ext}(z, q, \omega) + \int dz' v(z', z'; q, \omega) \right]$$

(2)

and

$$\delta n_{3D}(z, q, \omega) = \int dz' \chi_{3D}(z', z; q, \omega) \left[ \delta \Phi_{ext}(z', q, \omega) + \int dz'' v(z'', z'; q, \omega) \right].$$

(3)

Here, \(q\) is the magnitude of the 2D wave vector parallel to the surface, \(\chi_{2D}(q, \omega)\) and \(\chi_{3D}(z, z'; q, \omega)\) are 2D and 3D interacting density response functions, respectively, \(\delta \Phi_{ext}(z, q, \omega)\) is the 2D Fourier transform of the external potential \(\delta \Phi_{ext}(r, \omega)\), and \(v(z, z'; q)\) is the 2D Fourier transform of the bare Coulomb interaction

$$v(z, z'; q) = v_q e^{-|z-z'|},$$

(4)

with \(v_q = 2\pi/q\).

Combining Eqs. (2) and (3), we find

$$\delta n_{2D}(z, q, \omega) = \delta (z - z_d) \chi_{eff}(q, \omega) \tilde{\phi}(z, q, \omega),$$

(5)

where

$$\chi_{eff}(q, \omega) = \frac{\chi_{2D}(q, \omega)}{1 - \chi_{2D}(q, \omega) W(z_d, z_d; q, \omega) - v_q},$$

(6)

\(W(z_d, z_d; q, \omega)\) being the so-called screened interaction

$$W(z, z'; q, \omega) = v(z, z'; q) + \int dz_1 \int dz_2 \times v(z, z_1; q) \chi_{3D}(z, z_2; q, \omega) v(z_2, z'; q),$$

(7)

and \(\tilde{\phi}(z, q, \omega)\) being the 2D Fourier transform of the total potential at \(z\) in the absence of the 2D sheet

$$\tilde{\phi}(z, q, \omega) = \int dz'' \left[ \delta (z - z'') + \int dz''' v(z, z'''; q) \times \chi_{3D}(z'', z'''; q, \omega) \right] \delta \Phi_{ext}(z'', q, \omega).$$

(8)

Equation (5) suggests that the screening of the 3D subsystem can be incorporated into the description of the electron-density response at the 2D electron gas through the introduction of the effective density-response function of Eq. (6), whose poles should correspond to 2D electron-density oscillations.

Alternatively, we can focus on the 2D Fourier transform of the total potential at \(z\) in the presence of both 2D and 3D subsystems

$$\delta \phi(z, q, \omega) = \delta \Phi_{ext}(z, q, \omega) + \int dz' v(z, z'; q) \left[ \delta n_{2D}(z', q, \omega) + \delta n_{3D}(z', q, \omega) \right],$$

(9)

which with the aid of Eqs. (3) and (8) can also be expressed in the following way:

$$\delta \phi(z, q, \omega) = \tilde{\phi}(z, q, \omega) + \int dz' W(z, z'; q, \omega) \delta n_{2D}(z', q, \omega).$$

(10)

Now we choose \(z = z_d\) and using Eq. (5) we write

$$\delta \phi(z, q, \omega) = [1 + W(z_d, z_d; q, \omega) \chi_{eff}(q, \omega)] \tilde{\phi}(z_d, q, \omega),$$

(11)

which allows one to introduce the effective inverse 2D dielectric function

$$\varepsilon_{2D}^{-1}(q, \omega) = 1 + W(z_d, z_d; q, \omega) \chi_{eff}(q, \omega).$$

(12)

Since our aim is to investigate the occurrence of long-wavelength \((q \rightarrow 0)\) collective excitations, we can rely on the random-phase approximation (RPA),\(^{12}\) which is exact in the \(q \rightarrow 0\) limit. In this approximation, the 2D and 3D interacting density-response functions are obtained as follows:

$$\chi_{2D}(q, \omega) = \frac{\chi_0^{2D}(q, \omega)}{1 - \chi_0^{2D}(q, \omega) v_q}$$

(13)

and

$$\chi_{3D}(z, z'; q, \omega) = \chi_0^{3D}(z, z'; q, \omega) + \int dz_1 \int dz_2 \times \chi_0^{3D}(z_2, z'; q, \omega) \chi_0^{2D}(z_1, z_2; q, \omega).$$

(14)

where \(\chi_0^{2D}(q, \omega)\) and \(\chi_0^{3D}(z, z'; q, \omega)\) represent their noninteracting counterparts. An explicit expression for the 2D noninteracting density-response function \(\chi_0^{2D}(q, \omega)\) was reported by Stern.\(^{13}\) In order to derive explicit expressions for the 3D noninteracting density-response function \(\chi_0^{3D}(z, z'; q, \omega)\) one needs to rely on simple models, such as the hydrodynamic or infinite-barrier model, but accurate numerical calculations have been carried out\(^{14,15}\) from the knowledge of the eigen-
functions and eigenvalues of the Kohn-Sham Hamiltonian of density-functional theory (DFT).  

Combining Eqs. (6), (12), and (13), one finds the RPA effective 2D dielectric function

\[ \epsilon_{\text{eff}}(q, \omega) = 1 - W(z_d; z_d; q; \omega) \chi_{2D}(q, \omega). \]  

(15)

The longitudinal modes of the 2D subsystem, or plasmons, are solutions of

\[ \epsilon_{\text{eff}}(q, \omega) = 0. \]  

(16)

In the absence of the 3D subsystem, the long-wavelength limit of the effective 2D dielectric function of Eq. (15) is found to have two zeros. One zero corresponds to a high-frequency (\( \omega \gg v_F q \)) oscillation in which both 2D and 3D electrons oscillate out of phase. The other mode corresponds to a low-frequency acoustic oscillation in which both 2D and 3D electrons oscillate out of phase.

At high frequencies, where \( \omega \gg v_F q \), the long-wavelength limit of the 2D density-response function \( \chi_{2D}(q, \omega) \) is known to be

\[ \lim_{q \to 0} \chi_{2D}^0(q, \omega \gg v_F q) = \frac{1}{\omega_q^2} \frac{\omega^2}{\omega^2 - \omega_p^2}. \]  

(18)

On the other hand, when the 2D sheet is located either far inside or far outside the metal surface, the long-wavelength limit of the 3D screened interaction \( W(z_d; z_d; q, \omega) \) takes the form

\[ \lim_{q \to 0} W(z_d; z_d; q, \omega \gg v_F q) = v_q \frac{\omega^2}{\omega^2 - \omega_p^2}, \]  

(19)

where \( \omega_p \) represents either the bulk-plasmon frequency \( \omega_p = \sqrt{4\pi n} \) or the conventional surface-plasmon energy \( \omega_z = \omega_p / \sqrt{2} \), depending on whether the 2D sheet is located inside or outside the solid. Introduction of Eqs. (18) and (19) into Eqs. (15) and (16) yields a high-frequency mode at

\[ \omega^2 = \omega_p^2 + \omega_{2D}^2. \]  

(20)

At low frequencies, we seek for an acoustic 2D plasmon energy that in the long-wavelength limit takes the form

\[ \omega = v_F q. \]  

(21)

A careful analysis of the 2D density-response function \( \chi_{2D}^0(q, \omega) \) and the 3D screened interaction \( W(z_d; z_d; q, \omega) \) shows that at \( \omega = v_F q \) the long-wavelength limits of these quantities take the form

\[ \lim_{q \to 0} \chi_{2D}^0(q, \omega \gg v_F q) = \frac{1}{\pi} \left[ \frac{\alpha}{\alpha^2 - 1} \right], \]  

(22)

and

\[ \lim_{q \to 0} W(z_d; z_d; q, \omega \gg v_F q) = I(z_d). \]  

(23)

An inspection of Eqs. (15), (22), and (23) indicates that for a low-energy acoustic oscillation to occur the quantity \( I(z_d) \) must be different from zero. In that case, the long-wavelength limit of the effective 2D dielectric function of Eq. (15) has indeed a zero corresponding to a low-frequency oscillation of energy given by Eq. (21) with

\[ \alpha = \sqrt{1 + \frac{[I(z_d)]^2}{\pi [\pi + 2I(z_d)]}}. \]  

(24)

In the following, we investigate the impact of the 3D screening on the actual wave-vector dependence of the low-energy 2D collective excitation. We first consider the two limiting cases in which the 2D sheet is located far inside and far outside the metal surface, and we then carry out self-consistent calculations of the 3D screened interaction \( W(z_d; z_d; q, \omega) \), which will allow us to obtain plasmon dispersions for arbitrary locations of the 2D sheet.

A. 2D sheet far inside the metal surface

In the case of a 2D sheet that is located far inside the metal surface, the 3D subsystem can safely be assumed to exhibit translational invariance in all directions, i.e., the screened interaction \( W(z_d; z_d; q, \omega) \) entering Eq. (15) can be easily obtained from the knowledge of the interacting density-response function \( \chi_{3D}(k, \omega) \) of a uniform 3D electron gas, as follows:

\[ W(z_d; z_d; q, \omega) = 2 \int \frac{dq_z}{k^2} \epsilon_{3D}^{-1}(k, \omega), \]  

(25)

where \( k = \sqrt{q^2 + q_z^2} \) is the magnitude of a 3D wave vector and \( \epsilon_{3D}^{-1}(k, \omega) \) is the inverse dielectric function of a uniform 3D electron gas

\[ \epsilon_{3D}^{-1}(k, \omega) = 1 + \frac{4\pi}{k^2} \chi_{3D}(k, \omega). \]  

(26)

In the RPA,

\[ \epsilon_{3D}(k, \omega) = 1 - \frac{4\pi}{k^2} \chi_{3D}^0(k, \omega). \]  

(27)

\( \chi_{3D}(k, \omega) \) being the noninteracting density-response function first obtained by Lindhard.  

1. Local 3D response

If one characterizes the 3D uniform electron gas by a local dielectric function \( \epsilon_{3D}(\omega) \), then Eq. (25) yields

\[ W_{\text{local}}(z_d; z_d; q, \omega) = v_q \epsilon_{3D}^{-1}(\omega). \]  

(28)

In a 3D gas of free electrons, \( \epsilon_{3D}(\omega) \) takes the Drude form.
\[ \epsilon_{\text{3D}}(\omega) = 1 - \frac{\omega_p^2}{\omega^2}, \]  

which yields

\[ \lim_{q \to 0} W_{\text{local}}(z_d, z_d; q, \alpha v_F q) = 0. \]  

This means that in a local picture of the 3D response the characteristic collective oscillations of the 2D electron gas would be completely screened by the surrounding 3D substrate and no low-energy acoustic mode would exist.\(^{19}\)

2. Hydrodynamic 3D response

Dispersion effects of the 3D subsystem can be incorporated approximately in a hydrodynamic model. In this approximation, the dielectric function of a 3D uniform electron gas is found to be\(^{18}\)

\[ \epsilon_{\text{3D}}(k, \omega) = 1 - \frac{\omega_p^2}{\omega^2 - \beta^2 k^2}, \]  

where \(\beta = \sqrt{1/3k_F}\) represents the speed of propagation of hydrodynamic disturbances in the electron system,\(^{20}\) and \(k_F\) is the 3D Fermi momentum.

Introducing Eq. (31) into Eq. (25), one finds

\[ \lim_{q \to 0} W(\zeta_d, \zeta_d; q, \alpha v_F q) = 2 \pi \beta / \omega_p, \]  

which yields the following simple expression for the acoustic coefficient of Eq. (24):

\[ \alpha = \sqrt{1 + \frac{4 \beta^2 / \omega_p^2}{1 + 4 \beta^2 / \omega_p^2}}. \]  

3. Full 3D response

We have carried out numerical calculations of the RPA effective dielectric function of Eq. (15), by using the full \(\chi_{\text{2D}}^0(q, \omega)\) and \(\chi_{\text{3D}}^0(k, \omega)\) density-response functions, and choosing the electron-density parameters \(\tilde{r}_{\text{2D}}=3.14\) and \(r_{\text{3D}}=1.87\) corresponding to the (0001) surface of Be.\(^{21}\)

The results we have obtained with \(\omega=0.01\alpha_0^{-1}\) and \(q=0.1\alpha_0^{-1}\) are displayed in Figs. 1(a) and 1(b), respectively. We observe that at energies below the upper edge \(\omega_{\omega_e} = v_F q + q^2/(2m)\) (vertical dashed line) of the 2D e-h pair continuum (where 2D e-h pairs can be excited) the real part of the effective dielectric function is nearly constant and the imaginary part is large, as would occur in the absence of the 3D substrate. At energies above \(\omega_{\omega_e}\) momentum and energy conservation prevents 2D e-h pairs from being produced, and Im \(\epsilon_{\text{eff}}(q, \omega)\) is very small.

Collective excitations are related to a zero of Re \(\epsilon_{\text{eff}}(q, \omega)\) in a region where Im \(\epsilon_{\text{eff}}(q, \omega)\) is small and lead, therefore, to a maximum in the energy-loss function Im[\(-\epsilon_{\text{eff}}(q, \omega)\)].\(^{22}\) In the absence of the 3D substrate, a 2D plasmon would occur at \(\omega_{\text{2D}}=1.22\) eV for \(q=0.01\alpha_0^{-1}\) and \(\omega_{\text{2D}}=3.99\) eV for \(q=0.1\alpha_0^{-1}\). However, Fig. 1 shows that in the presence of the 3D substrate a well-defined low-energy acoustic plasmon occurs, the sound velocity being just over the 2D Fermi velocity \(v_F\). The small width of the plasmon peak is entirely due to plasmon decay into e-h pairs of the 3D substrate.

We have carried out calculations of the effective 2D dielectric function of Eq. (15) for a variety of 2D and 3D electron densities, and we have found that a well-defined acoustic plasmon of energy \(\omega =\alpha v_F q\) is always present for 2D wave vectors up to a maximum value of \(q - q_e\) where the acoustic-plasmon dispersion merges with \(\omega_{\omega_e}\). The coefficient \(\alpha\) that we have obtained from the zeros in Eq. (16) is represented by stars in Fig. 2 versus the 3D Wigner radius \(r_{\text{3D}}\), together with the prediction of Eq. (24) as obtained with the computed RPA value of \(l(z_d - \infty)\) (solid line) and the hydrodynamic prediction of Eq. (33) (dotted line). Figure 2 shows that Eq. (33) is a good representation of the linear dispersion of this low-energy plasmon, especially at the highest 3D electron densities. Figure 2 also shows that for low electron densities the hydrodynamic prediction is too small, which is due to the fact that at low densities the long-wavelength limit of the 3D screened interaction is underestimated in this approximation.

B. 2D sheet far outside the metal surface

In the case of a 2D sheet that is located far outside the metal surface, where the 3D electron density is negligible, the 3D screened interaction of Eq. (7) at \(z=z'=z_d\) takes the form

\[ W(\zeta_d, \zeta_d; q, \alpha v_F q) = v_q \left[ 1 - e^{-2q z_d g(q, \omega)} \right], \]  

where \(g(q, \omega)\) is the so-called surface-response function of the 3D subsystem

\[ g(q, \omega) = -\int_0^d dz_1 \int d\zeta_2 e^{i (\zeta_1 - \zeta_2) v_{\text{3D}}(\zeta_1, \zeta_2; q, \omega)}. \]  

1. Local 3D response

In the simplest possible model of a metal surface, one characterizes the 3D substrate at \(z \leq 0\) by a local dielectric function which jumps discontinuously at the surface from \(\epsilon_{\text{3D}}(\omega)\) inside the metal \((z \leq 0)\) to zero outside \((z > 0)\). Within this model,\(^{23}\)

\[ g_{\text{local}}(q, \omega) = \frac{\epsilon_{\text{3D}}(\omega) - 1}{\epsilon_{\text{3D}}(\omega) + 1}, \]  

which is precisely the long-wavelength limit of the actual surface-response function.

At low frequencies, where \(\epsilon_{\text{3D}}(\omega)\) is large [see Eq. (29)] and \(g_{\text{local}}(q, \omega)\to 1\), Eq. (34) yields

\[ \lim_{q \to 0} W_{\text{local}}(\zeta_d, \zeta_d; q, \alpha v_F q) = 4 \pi z_d. \]  

Introducing Eq. (37) into Eq. (24), one finds
For large values of the distance $z_d$ between the 2D sheet and the metal surface, one can write

$$\alpha = \sqrt{1 + \frac{16z_d^2}{1 + 8z_d^2}}.$$

For large values of the distance $z_d$ between the 2D sheet and the metal surface, one can write

$$\alpha \approx \sqrt{2z_d},$$

which is the result first obtained by Chaplik\(^3\) by using the Drude-like 2D density-response function of Eq. (18).

**2. Nonlocal 3D response**

An inspection of Eq. (34) shows that the long-wavelength limit of the screened interaction $W(z_d, q, \omega)$ is dictated not only by the local ($q=0$) surface-response function $g^{\text{local}}(q, \omega)$ but also by the leading correction in $q$ of the actual nonlocal $g(q, \omega)$. Feibelman showed that up to first order in an expansion in powers of $q$, the surface-response function of a jellium surface can be written as\(^24\)

$$g(q, \omega) = \frac{\epsilon_{3D}(\omega)}{\epsilon_{3D}(\omega) + 1} \left[ 1 + 2q d_\perp(\omega) \frac{\epsilon_{3D}(\omega)}{\epsilon_{3D}(\omega) + 1} \right] + O(q^2),$$

which at low frequencies yields
The frequency-dependent $d_\perp(\omega)$ function occurring in Eq. (40) represents the centroid of the induced 3D charge density, which in the static limit ($\omega=0$) reduces to the image plane of an external point charge.

Using Eq. (41), we find the actual long-wavelength limit of Eq. (34):

$$\lim_{q \to 0} W(z_d, z_d'; q, \omega F q) = 4\pi[z_d - d_\perp(0)],$$

which combined with Eq. (24) yields

$$\alpha = \sqrt{1 + \frac{16[z_d - d_\perp(0)]^2}{1 + 8[z_d - d_\perp(0)]}}.$$ (43)

This shows that the acoustic-plasmon sound velocity derived from the local model [see Eq. (38)] remains unchanged, as long as $z_d$ is replaced by the coordinate of the 2D sheet relative to the position of the image plane.

### 3. Full 3D response

In order to compute the full RPA surface-response function of Eq. (35), we follow the method described in Ref. 14 for a jellium slab. We first assume that the 3D electron density-response function. We then introduce a double-cosine Fourier representation for both the noninteracting and the interacting density-response functions, and find explicit expressions for the surface-response function in terms of the Fourier coefficients of the density-response function. To ensure that our slab calculations are a faithful representation of the actual surface-response function of a semiinfinite 3D system, we follow the extrapolation procedure described in Ref. 28.

We have carried out numerical calculations of the effective dielectric function of Eq. (15), by using the full 2D noninteracting density-response function, $\chi^{3D}_0(q, \omega)$, and the self-consistent RPA surface-response function, $g(q, \omega)$, with electron-density parameters $r_s^{3D}=3.14$ and $r_s^{3D}=1.87$ corresponding to Be(0001).

The results we have obtained for a 2D sheet located at $z_d=\lambda_F$ are displayed in Figs. 3(a) (with $q=0.01a_0^{-1}$) and 3(b) (with $q=0.1a_0^{-1}$), $\lambda_F=2\pi/k_F$ being the 3D Fermi wavelength. Figure 3 clearly shows that in the presence of the 3D substrate a well-defined low-energy acoustic plasmon occurs, the sound velocity being close to that predicted by Eq. (43) with $d_\perp(0)=0.2\lambda_F$ (vertical long-dashed lines). The actual plasmon energy is smaller than predicted by Eq. (43), especially at the shortest wavelengths ($q=0.1a_0^{-1}$), simply due to the bending of the plasmon dispersion as a function of $q$ (see Fig. 7 below).

C. 2D sheet at an arbitrary location

1. Hydrodynamic 3D response

An explicit expression for the screened interaction $W(z, z'; q, \omega)$ of Eq. (7) can be obtained in a hydrodynamic model in which the 3D electron density is assumed to change abruptly at the surface from $n$ inside the metal to zero outside. After writing and linearizing the basic hydrodynamic equations, i.e., the continuity and the Bernoulli equation, we find

$$\lim_{q \to 0} W(z_d, z_d'; q, \omega F q) = \begin{cases} 
2 \pi \beta \frac{\omega \rho}{\omega F} (1 - e^{2z_d \omega \rho / \beta}), & z_d \leq 0, \\
4\pi z_d, & z_d > 0,
\end{cases}$$

where $W(z_d, z_d'; q, \omega F q)$ is zero inside the slab.

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![Graph showing the acoustic-plasmon energy as a function of $r_s^{3D}$](image-url)
solid ($z_d \leq 0$) and $4\pi z_d$ outside ($z_d > 0$). This shows that in
the 2D long-wavelength limit ($q \to 0$) the nonlocality of the
3D response is only present inside the solid ($z_d \leq 0$), where
finite values of the 3D momentum $k$ are possible.

Alternatively, the screened interaction $W(z, z^*; q, \omega)$ can
be obtained within a specular-reflection model (SRM)\textsuperscript{29} or,
equivalently, a classical infinite-barrier model (CIBM)\textsuperscript{30,31} of
the surface, which have the virtue of describing the 3D
screened interaction in terms of the bulk dielectric function $\varepsilon_{3D}(k, \omega)$ of a 3D uniform (and infinite) electron gas (see
Appendix). If this bulk dielectric function is chosen to be the
hydrodynamic dielectric function of Eq. (31), then these
models yield Eq. (44). A more accurate description of the
bulk dielectric function $\varepsilon_{3D}(k, \omega)$ yields a result that still co-
incides with that of Eq. (44) outside the surface ($z_d > 0$),
though small differences may arise at $z_d < 0$.

When the 2D sheet is located far inside the metal ($z_d \ll 0$), Eq. (44) yields the hydrodynamic asymptotic behavior
dictated by Eq. (32), and the SRM combined with the RPA
bulk dielectric function yields the correct RPA asymptotic
behavior. However, these hydrodynamic and specular-
reflection models, which are both based on the assumption
that the 3D electron density drops abruptly to zero at the
surface, fail to reproduce the correct asymptotic behavior
outside the surface [see Eq. (42)]. This is due to the fact that
the leading correction in $q$ of the surface-response function
$g(q, \omega)$ is governed by the spill out of the electron density
into the vacuum, which is not present in these models.

FIG. 3. As in Fig. 1, but now for a 2D sheet that is located at one 3D Fermi wavelength outside the metal surface ($z_d=\lambda_F$). The
long-dashed vertical lines here represent the plasmon energy $\omega=\omega_0 q$ predicted by Eq. (43) with $d_\perp=0.2\lambda_F$. For real frequencies, a 2D sheet
that is located at $z_d=\lambda_F$ exhibits a plasmon peak that at $q=0.01\alpha_0^{-1}$ is extremely sharp (as $z_d \to \infty$ the plasmon peak becomes a delta function); hence, in the calculations presented in this figure we have replaced the energy $\omega$ by a complex quantity $\omega+i\eta$ with (a) $\eta=0.05$ eV for $q =0.01\alpha_0^{-1}$ and (b) $\eta=0$ for $q=0.1\alpha_0^{-1}$.
2. Full 3D response

For an arbitrary location of the 2D sheet we need to compute the full screened interaction \( W(z_d,z_d';q,\omega) \) of Eq. (7). To calculate this quantity we consider a jellium slab, as we did to obtain the surface-response function \( g(q,\omega) \), and we find explicit expressions in terms of the Fourier coefficients of the interacting density-response function,\(^\text{27}\) which we compute in the RPA [see Eq. (14)] from the knowledge of the LDA eigenvalues and eigenfunctions of the Kohn-Sham Hamiltonian of DFT.

In Fig. 4, the long-wavelength limit \( I(z_d) \) of the screened interaction \( W(z_d,z_d';q,\omega) \) [see Eq. (23)] is displayed versus \( z_d' \), as obtained with \( r_3^{3D} = 1.87 \) from our full self-consistent RPA calculations (thick solid line) and from the hydrodynamic Eq. (44) (thin solid line). Far inside the solid, our full calculation is close to the hydrodynamic prediction (see also Fig. 2) and coincides with the result one obtains from the bulk screened interaction of Eq. (25) (horizontal dashed line). Near the surface, our full calculation considerably deviates from the hydrodynamic prediction and converges far outside the solid with the asymptotic curve dictated by Eq. (42) with \( d_{\perp}(0) = 0.2\lambda_F \) (dotted line).\(^\text{32}\)

At this point, it is interesting to note that within a local picture of the 3D response the long-wavelength \( I(z_d) \) screened interaction would be zero for all locations of the 2D sheet inside the metal \( z_d \leq 0 \), showing that the screening of 2D electron-density oscillations would be complete and no acoustic surface plasmon would occur. It is precisely the nonlocality of the 3D response (finite values of the 3D momentum \( k \)) that is still present in the 2D long-wavelength limit which provides incomplete screening and allows, therefore, the formation of acoustic surface plasmons in the interior of the solid. We also note that within a simple nonlocal picture of the 3D response, such as the hydrodynamic and specular-reflection models described above, the screening of 2D electron-density oscillations would still be complete at the jellium edge \( z_d = 0 \). Hence, in the real situation where the 2D surface-state band is located very near the jellium edge the occurrence of acoustic surface plasmons is originated by a combination of the nonlocality of the 3D response and the spill out of the 3D electron density into the vacuum.

Figures 5(a) and 5(b) exhibit the results we have obtained for the effective dielectric function of Eq. (15) (with \( q = 0.01a_0^{-1} \) [Fig. 5(a)] and \( q = 0.1a_0^{-1} \) [Fig. 5(b)]) by using the full 2D noninteracting density-response function \( \chi_{2D}^0(q,\omega) \) and the self-consistent RPA screened interaction \( W(z_d,z_d';q,\omega) \), with electron-density parameters \( r_s^{3D} = 3.14 \) and \( r_s^{3D} = 1.87 \) corresponding to Be(0001). In these figures the 2D sheet has been taken to be located at \( z_d = 0 \), as approximately occurs with the quasi-2D surface-state band in Be(0001). For comparison, also shown in these figures are the results we have obtained for the energy-loss function when the 2D sheet is located inside the metal at \( z_d = -\lambda_F \) and outside the metal at \( z_d = \lambda_F/2 \) and \( z_d = \lambda_F \).

An inspection of Fig. 5 shows that (i) the results we have obtained for \( z_d = -\lambda_F \) and \( z_d = \lambda_F \) are exactly reproduced by the limiting Eqs. (25) and (34) appropriate for a 2D sheet far inside and far outside the metal surface, respectively, and (ii) in the actual situation where the 2D surface-state band is located very near the jellium positive background edge \( z_d = 0 \), a well-defined low-energy acoustic plasmon occurs, the sound velocity being very close to the limiting case of a 2D sheet far inside the metal surface and being, therefore, just above \( \omega_s \). This is in agreement with the recent prediction that in a real metal surface where a partially occupied quasi-2D surface-state band coexists in the same region of space with the underlying 3D continuum an acoustic surface plasmon should occur at energies just above the upper edge of the 2D \( e-h \) pair continuum.\(^\text{6}\)

The sound velocity \( v_s(\omega = v_F q) \) of the acoustic plasmon that is visible in Fig. 5 is displayed in Fig. 6 versus the location \( z_d \) of the 2D sheet relative to the jellium edge, as obtained from our full RPA self-consistent calculation of the effective 2D dielectric function of Eq. (15) (open circles), together with the sound velocity \( v_s = v_F \) obtained from Eq. (43) with \( d_{\perp}(0) = 0.2\lambda_F \) (dotted line). When the 2D sheet is located inside the metal surface, the sound velocity nicely
The sound velocity of Fig. 6 (open circles) has been obtained from the effective 2D dielectric function at very low 2D momenta, where the energy of the acoustic plasmon is linear in $q$. The behavior of this plasmon energy as a function of the 2D momentum $q$ is displayed in Fig. 7, with the 2D sheet chosen to be located far inside the solid (thick dotted line), at $z_d=0$ (open circles), at $z_d=\lambda_F$ (solid line), and infinitely far outside the solid (solid circles). The upper edge of the 2D $e-h$ pair continuum is represented by a thick dashed line, showing that in the real situation where the 2D sheet is located near the jellium edge the energy of the acoustic surface plasmon (open circles) is just outside the 2D $e-h$ pair continuum for all momenta under study.
III. SUMMARY AND CONCLUSIONS

The partially occupied band of Shockley surface states in a variety of metal surfaces is known to form a quasi-2D electron gas that is immersed in a semiinfinite 3D gas of valence electrons. In order to describe the impact of the dynamical screening of the semi-infinite 3D continuum on the electronic excitations at the 2D electron gas of Shockley surface states, we have presented a model in which the dynamical screening of 3D valence electrons is incorporated through the introduction of an effective 2D dielectric function.

We have considered the two limiting cases in which the 2D sheet is located far inside and far outside the metal surface. In both cases, the dynamical screening of the valence electrons in the metal is found to change the 2D plasmon energy from its characteristic square-root behavior to a linear dispersion, the sound velocity being proportional to the Fermi momentum of the 2D gas. As this collective oscillation occurs in a region of 2D momentum space where 2D e-h pairs cannot be produced, this is a well-defined acoustic plasmon. The finite width of the plasmon peak is due to a small probability for the plasmon to decay into e-h pairs of the 3D substrate.

We have shown explicitly that when the 2D sheet coexists in the same region of space with the underlying 3D continuum the origin of acoustic surface plasmons, which have been overlooked over the years, is dictated by a combination of the nonlocality of the 3D response and the spill out of the 3D electron density into the vacuum, both providing incomplete screening of the 2D electron-density oscillations.

We have carried out self-consistent DFT calculations of the dynamical density-response function of the 3D system of valence electrons, and we have found that a well-defined acoustic surface plasmon exists for all possible locations of the 2D sheet relative to the metal surface. The energy dispersion of this acoustic surface plasmon is slightly higher than the

FIG. 6. The open circles represent the sound velocity \( v_s = \sqrt{\omega q} \) of the low-energy acoustic plasmon that is visible in Fig. 5 versus the location \( z_d \) of the 2D sheet with respect to the jellium edge. The horizontal short-dashed line represents the result we have obtained from the limiting Eq. (25) appropriate for a 2D sheet far inside the metal. The dotted line represents the result we have obtained from the limiting Eq. (43) with \( d_2 = 0.2k_F \), which is appropriate for a 2D sheet far outside the metal. The long-wavelength limit \( v_F \) of the upper edge \( \omega_q/q \) of the 2D e-h pair continuum is represented by an horizontal long-dashed line. The thick and thin solid lines represent the results obtained from Eq. (24) by using the actual RPA I\( (z_d) \) and the hydrodynamic Eq. (44), respectively, 2D and 3D electron densities have been taken to be those corresponding to the Wigner radii \( r_{s2D} = 3.14 \) and \( r_{s3D} = 1.87 \), respectively. The 2D effective mass has been taken to be \( m = 1 \).

FIG. 7. Dispersion of the acoustic plasmon occurring in a 2D sheet that is taken to be located far inside the solid (thick dotted line), at \( z_d = 0 \) (open circles), at \( z_d = \lambda_F \) (solid line), and infinitely far outside the metal (solid circles). The thick dashed line represents the upper edge \( \omega_q = \nu_{qF} / q \) of the 2D e-h pair continuum. The thin dotted line represents the 2D plasmon energy \( \omega_{2D} \) dictated by Eq. (17), which is accurate at long wavelengths \( q \rightarrow 0 \). The thin dashed line represents the 2D plasmon energy \( \sqrt{\omega_{2D}^2 + 3\nu_{qF}^2} / 4 \) that is obtained after an expansion of \( \chi_{2D}(q, \omega) \) in powers of \( \nu_{qF} / \omega \). 2D and 3D electron densities have been taken to be those corresponding to the Wigner radii \( r_{s2D} = 3.14 \) and \( r_{s3D} = 1.87 \), respectively. The 2D effective mass has been taken to be \( m = 1 \).
nergy of the collective excitation that has recently been predicted to exist at real metal surfaces where a quasi-2D surface-state band coexists with the underlying 3D continuum. Small differences between the plasmon energies obtained here and those reported previously are due to the absence in the present model of transitions between 2D and 3D states.

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APPENDIX: SPECULAR-REFLECTION MODEL OF THE 3D RESPONSE

Either by assuming that electrons are specularly reflected at the surface (SRM) or by invoking the so-called classical infinite-barrier model (CIBM) of a jellium surface, one finds

\[
W(z_d; z_d'; q, \omega) = v_\parallel \left\{ \begin{array}{ll}
1 - e^{-2q z_d} \{ 1 - \epsilon_i(0; \omega) \} / [1 + \epsilon_i(0; \omega)], & z_d \geq 0,

\epsilon_i(0; q, \omega) + \epsilon_i(2z_d'; q, \omega) - 2\epsilon_i^2(z_d'; q, \omega) / [\epsilon_i(0; q, \omega) + 1], & \text{elsewhere},
\end{array} \right.
\]

(A1)

where \( k = \sqrt{q^2 + q_z^2} \) is a 3D momentum and

\[
\epsilon_i(z; q, \omega) = \frac{q}{\pi} \int_{-\infty}^{+\infty} dq_z e^{iq_z z} \epsilon_i^1(k, \omega),
\]

(A2)

\( \epsilon_i^1(k, \omega) \) being the dielectric function of a uniform (and infinite) 3D electron gas.

If the 3D dielectric function \( \epsilon_{3D}(q, \omega) \) is chosen to be the hydrodynamic dielectric function of Eq. (31), then one finds

\[
\epsilon_i(z; q, \omega) = \frac{1}{\omega^2 - \omega_p^2} \left[ \frac{\epsilon_i^1(k, \omega)}{\sqrt{\beta^2 q^2 + \omega_p^2 - \omega^2}} \right] e^{-\beta q z_i},
\]

(A3)

which in combination with Eq. (A1) yields Eq. (44).

10. The sound velocity of this acoustic mode is, however, close to the Fermi velocity of the 2D surface-state band, which is typically a few orders of magnitude larger than the sound velocity of acoustic phonons in metals.
19. If one replaces the dielectric function \( \epsilon_{3D}(q, \omega) \) entering Eq. (28) by a constant \( \kappa \) and expands \( \epsilon_{3D}^1(q, \omega) \) in powers of \( v_F q / \omega \), Eq. (16) is easily found to yield the plasmon dispersion \( \omega^2 = \omega_{3D}^2 / (\kappa + 3v_F^2 q^2 / 4) \) (see Ref. 13). This suggests that at low frequencies, where the dielectric constant \( \kappa \) is large, an acoustic plasmon should be expected to occur at \( \omega = \sqrt{3/4} v_F q \); however, at these low frequencies, where \( \omega < v_F q \), the plasmon dispersion fails. Furthermore, a careful analysis of the long-wavelength behavior of \( \epsilon_{3D}^1(q, \omega) \) shows that an infinitely large dielectric constant \( \kappa \) yields an effective 2D dielectric function which has no zeros, so that no acoustic plasmon occurs in this model.
20. The value \( \beta = \sqrt{3/5} k_F \) is usually chosen to describe processes in which high frequencies of the order of the 3D plasma frequency are involved. For the low energies of interest here, however, the hydrodynamic value \( \beta = \sqrt{1/3} k_F \) should be more appropriate.
On Be(0001), an occupied surface state with a binding energy of 2.8 eV at \( \bar{\Gamma} \) exists in the \( \Gamma^*_3 - \Gamma^*_4 \) bulk band gap. This surface state disperses with momentum parallel to the surface, thereby forming a surface-state band with a 2D Fermi energy \( \varepsilon_F = 2.8 \) eV. If one takes, for simplicity, the effective mass of surface-state electrons to be equal to the free-electron mass, the 2D Fermi momentum \( q_F \) and Wigner radius \( r_{2D} \) are found to be \( q_F = 0.45 a_0^{-1} \) and \( r_{2D} = 3.14 \), respectively. On the other hand, Be has two valence electrons per atom, which yields an average 3D electron density corresponding to the 3D Wigner radius \( r_{3D} = 1.87 \).

The energy-loss function \( \text{Im}[-e^{-1}(q, \omega)] \) is not necessarily positive definite and may not give the true absorptive response of the combined 2D and 3D systems; however, its resonant structure is a true reflection of the modes of the system.


\( z_0 \) is chosen sufficiently large for the physical results to be insensitive to the precise value employed.


The image-plane coordinate \( d_{\perp}(0) = 0.2 \lambda_F \) has been chosen in such a way that Eq. (42) reproduces the asymptotic behaviour of the full RPA calculation represented in Fig. 4 by a thick solid line.

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